## **CLAIMS**

What is claimed:

1.	An immersive scanning device for imaging a scene comprising:				
a head	unit configured to receive an image light beam and generate an image data				
signal,	said head unit comprising a rotating mirror for receiving said image light				
beam a	beam and an optical receiver for receiving said image light beam from said mirror				
and ou	atputting said image pixel data signal in response thereto, said image data				
signal	comprises a pixel image signal and a pixel distance signal; and				
a supp	ort unit for supporting and rotating said head unit.				

The immersive scanning device of claim 1, wherein said optical receiver

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3. The immersive scanning device of claim 2, wherein said distance generation unit comprises a distance detection unit for generating said pixel distance data signal.

further comprises a distance generation unit for generating said pixel distance data signal.

4. The immersive scanning device of claim 1, wherein said optical receiver further comprises a two dimensional imager for generating a depth image representative of the distance of an object depicted by said pixel image signal from said head unit.

1	5.	The immersive scanning device of claim 1, wherein said depth image
2	comprises a p	olar plot depicting the distance of a plurality of objects represented by said
3	pixel image si	gnal from said head unit.
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1	6.	The immersive scanning device of claim 2, wherein said image pixel data
2	represents one	e pixel of captured image data.
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1	7.	The immersive scanning device of claim 6, wherein said pixel distance
2	data represent	s the distance of an object depicted by said pixel from said head unit.
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1	8.	The immersive scanning device of claim 2, further comprising a control
2	system for co	ntrolling said head unit and said support unit.
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1	9.	The immersive scanning device of claim 2, wherein said optical receiver
2	comprises an	imager for receiving said image light beam and generating said pixel image
3	data.	
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1	10.	The immersive scanning device of claim 9, wherein said imager comprises
2	a photomultip	olier tube(PMT).
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1	11.	The immersive scanning device of claim 9, wherein said imager comprises
2	a plurality of	imagers.

1	12.	The immersive scanning device of claim 2, further comprising a motor for			
2	rotating said	mirror in accordance with said control system.			
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1	13.	The immersive scanning device of claim 2, wherein said optical receiver			
2	further comp	rises an aperture screen for limiting the amount of said image light beam that			
3	is received by said imager.				
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1	14.	The immersive scanning device of claim 13, wherein said aperture screen			
2	comprises an	aperture of a predetermined size and shape.			
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1	15.	The immersive scanning device of claim 13, wherein said aperture			
2	comprises a s	quare shaped aperture.			
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1	16.	The immersive scanning device of claim 12, wherein said mirror			
2	comprises a 4	5° angled mirror.			
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1	17.	The immersive scanning device of claim 12, wherein said motor rotates			
2	between 1000	and 12,000 revolutions per minute during an image capture operation.			
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1	18.	The immersive scanning device of claim 2, further comprising a user			
2	interface for i	nputting control variable information.			

1	19. The immersive scanning device of claim 18, wherein said user interface				
2	comprises a graphical user interface (GUI).				
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1	20. The immersive scanning device of claim 17, wherein said pixel image				
2	signal comprises data representative of a plurality of pixels captured during one				
3	revolution of said mirror.				
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1	21. The immersive scanning device of claim 17, wherein said pixel image				
2	signal comprises data representative of 64,000 pixels captured during one revolution of				
3	said mirror.				
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1	22. The immersive scanning device of claim 17, wherein said camera support				
2	further comprises a sweep motor for rotating said head unit about a predetermine axis of				
3	rotation.				
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1	23. The immersive scanning device of claim 22, wherein said sweep motor is				
2	controlled by said control system.				
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1	24. A method of capturing an immersive representation of a scene comprising				
2	the steps of:				
3	generating a distance detection light beam;				
4	transmitting said distance detection light beam toward an object within a scene;				
5	receiving an image light beam reflected from said object;				
6	receiving said distance light beam reflected from said object;				
7	providing a limited portion of said image light beam to an imager to produce an				
8	image pixel signal representative of a portion of said scene; and				
9	providing said distance light beam reflected from said object to a position sensing				
10	device to produce a distance signal representative of the distance of said object as				
11	depicted by said image pixel signal from a predetermined point.				
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1	25. The method of claim 24, further comprising the step of outputting said				
2	image pixel data signal and said pixel distance signal as an image data signal.				
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1	26. The method of claim 24, further comprising the step of storing said image				
2	data signal to a storage medium.				
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1	27. The method of claim 24, wherein said step of providing comprises the step				
2	of providing a limited portion of said image light beam to an imager to produce a				
3	plurality of image pixel signals representative of one pixel of said scene.				
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1	28. The method of claim 24, wherein said portion of said scene comprises a				
2	single pixel.				
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1	29. An immersive scanning device for imaging a scene comprising:				
2	a head unit receiving an image light beam and generating an image data signal;				
3	a support unit for supporting and rotating said head unit;				
4	said head unit comprises a rotating mirror for receiving said image light beam;				
5	an optical receiver for receiving said image light beam from said mirror and				
6	outputting said image pixel data signal in response thereto; and				
7	a control system for controlling the rotation of said head unit and said mirror in				
8	accordance with predetermined control variable information.				
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1	30. An immersive scanning device according to claim 29, further comprising a				
2	user interface for inputting said control variable information.				
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1	31. An immersive scanning device according to claim 29, further comprising a				
2	storage memory for storing sad control variable information.				
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1	32. An immersive scanning device according to claim 30, wherein said user				
2	interface comprises a graphical user interface.				
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from said control system.

1	33.	An immersive scanning device according to claim 30, wherein said optical			
2	receiver comprises an imager responsive to an image light beam for generating a image				
3	pixel data signal.				
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1	34.	An immersive scanning device according to claim 33, wherein said optical			
2	receiver further comprises an aperture screen for limiting the amount of image light that				
3	is received by said imager.				
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1	35.	An immersive scanning device according to claim 34, wherein said optical			
2	receiver further comprises a focusing lens for focusing an image light beam onto said				
3	aperture scree	n.			
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1	36.	An immersive scanning device according to claim 35, wherein said optical			
2	receiver furth	er comprises a distance detection unit for detecting the distance of an object			
3	relative to said	d head unit.			
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1	37.	An immersive scanning device according to claim 36, wherein said imager			
2	comprises a p	hotomultiplier tube (PMT).			
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1	38.	An immersive scanning device according to claim 37, wherein said head			
2	unit further co	omprises a scan motor for rotating said mirror in accordance with a signal			

1	39. An immersive scanning device according	ng to	claim	38,	wherein	said
2	support unit further comprises a sweep motor for rotating	g said	head	unit	in accord	lance
3	with a signal from said control system.					

1 40. An immersive scanning device according to claim 39, further comprising

2 an image data storage unit for storing image pixel data representative of a captured scene.